

Ch2. Random Vectors and Matrices

1 Definition

Definition 1.1 *A random vector or random matrix is a vector or matrix whose elements are random variables.*

In formally, a **random variable** is defined as a variable whose value depends on the outcome of a chance experiment. (Formally, a random variable is a function defined for each element of a sample space.)

In terms of experimental structure, we have two kinds of random vectors:

1. A vector containing a measurement on each of n different individuals or experimental units. When the same variable is observed on each of n units selected at random, the n random variables y_1, y_2, \dots, y_n in the vector are typically uncorrelated and have the same variance.

2. A vector consisting of p different measurements on one individual or experimental unit. The p random variables thus obtained are typically correlated and have different variables.

2 Means, Variances, Covariances, and Correlations (univariate)

Let $f(y)$ denote the density of the random variable y , the mean or expected value of y is defined as

$$\mu = E(y) = \int_{-\infty}^{\infty} yf(y)dy.$$

In general, for a function $u(y)$, we have

$$E[u(y)] = \int_{-\infty}^{\infty} u(y)f(y)dy.$$

A variance of a random variable y is defined as

$$\sigma^2 = var(y) = E(y - \mu)^2.$$

A square root of the variance is called the standard deviation,

$$\sigma = \sqrt{\text{var}(y)} = \sqrt{E(y - \mu)^2}.$$

For any two variables y_i and y_j , the covariance is

$$\sigma_{ij} = \text{cov}(y_i, y_j) = E[(y_i - \mu_i)(y_j - \mu_j)].$$

To standardize σ_{ij} , we divide it by (the product of) the standard deviations of y_i and y_j to obtain the correlation

$$\rho_{ij} = \text{corr}(y_i, y_j) = \frac{\sigma_{ij}}{\sigma_i \sigma_j}.$$

The random variable y_i and y_j are said to be independent if their joint density factors into the product of their marginal densities:

$$f(y_i, y_j) = f_i(y_i) f_j(y_j),$$

where the marginal density $f_i(y_i)$ is defined as

$$f_i(y_i) = \int_{-\infty}^{\infty} f(y_i, y_j) dy_j.$$

The independence implies the following two properties:

1. $E(y_i y_j) = E(y_i)E(y_j)$ if y_i and y_j are independent.
2. $\sigma_{ij} = \text{cov}(y_i, y_j) = 0$ if y_i and y_j are independent.

Note that the converse of the second property is not true in general; that is, $\sigma_{ij} = 0$ does not imply independence. It is only true in the case that y_i and y_j have a bivariate normal distribution.

3 Mean Vectors and Covariance Matrices for Random Vectors

3.1 Mean vector

$$E(\mathbf{y}) = E \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_p \end{pmatrix} = \begin{pmatrix} E(y_1) \\ E(y_2) \\ \vdots \\ E(y_p) \end{pmatrix} = \begin{pmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_p \end{pmatrix} = \boldsymbol{\mu},$$

where $E(y_i) = \mu_i$.

For the mean vectors, we have

$$E(\mathbf{x} + \mathbf{y}) = E(\mathbf{x}) + E(\mathbf{y}).$$

By analogy with $E(\mathbf{y})$, we define the expected value of a random matrix \mathbf{Z} as the

matrix of expected values:

$$E(\mathbf{Z}) = E \begin{pmatrix} z_{11} & z_{12} & \cdots & z_{1p} \\ z_{21} & z_{22} & \cdots & z_{2p} \\ \vdots & \vdots & & \vdots \\ z_{n1} & z_{n2} & \cdots & z_{np} \end{pmatrix} = \begin{pmatrix} E(z_{11}) & E(z_{12}) & \cdots & E(z_{1p}) \\ E(z_{21}) & E(z_{22}) & \cdots & E(z_{2p}) \\ \vdots & \vdots & & \vdots \\ E(z_{n1}) & E(z_{n2}) & \cdots & E(z_{np}) \end{pmatrix}$$

3.2 Covariance Matrix

$$E[(\mathbf{y} - \boldsymbol{\mu})(\mathbf{y} - \boldsymbol{\mu})'] = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \cdots & \sigma_{1p} \\ \sigma_{21} & \sigma_{22} & \cdots & \sigma_{2p} \\ \vdots & \vdots & & \vdots \\ \sigma_{p1} & \sigma_{p2} & \cdots & \sigma_{pp} \end{pmatrix} = \boldsymbol{\Sigma},$$

where $\sigma_{ii} = \text{var}(y_i)$ and $\sigma_{ij} = \text{cov}(y_i, y_j)$.

3.3 Generalized Variance

A measure of overall variability in the population of \mathbf{y} 's can be defined as the determinant of Σ :

$$\textit{Generalized variance} = |\Sigma|.$$

If $|\Sigma|$ is small, the \mathbf{y} 's are concentrated closer to $\boldsymbol{\mu}$ than if $|\Sigma|$ is large. A small value of $|\Sigma|$ may also indicate that the variables y_1, y_2, \dots, y_p in \mathbf{y} are highly intercorrelated, in which case the \mathbf{y} 's tend to occupy a subspace of the p dimensions.

3.4 Standardized Distance

To obtain a useful measure of distance between \mathbf{y} and $\boldsymbol{\mu}$, we need to take into account the variance and covariance of the y_i 's in \mathbf{y} . The standardized distance is defined as

$$\textit{Standardized distance} = (\mathbf{y} - \boldsymbol{\mu})' \Sigma^{-1} (\mathbf{y} - \boldsymbol{\mu}).$$

This distance is often called a Mahalanobis distance.

3.5 Correlation Matrices

The correlation matrix is defined as

$$\mathbf{P}_\rho = (\rho_{ij}) = \begin{pmatrix} 1 & \rho_{12} & \cdots & \rho_{1p} \\ \rho_{21} & 1 & \cdots & \rho_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ \rho_{p1} & \rho_{p2} & \cdots & 1 \end{pmatrix},$$

where $\rho_{ij} = \sigma_{ij}/[\sigma_i\sigma_j]$. If we define

$$\mathbf{D}_\sigma = \text{diag}(\sigma_1, \sigma_2, \cdots, \sigma_p),$$

we have

$$\mathbf{P}_\rho = \mathbf{D}_\sigma^{-1} \boldsymbol{\Sigma} \mathbf{D}_\sigma^{-1},$$

and

$$\boldsymbol{\Sigma} = \mathbf{D}_\sigma \mathbf{P}_\rho \mathbf{D}_\sigma.$$

4 Linear Functions of Random Vectors

4.1 Means

Theorem 4.1 *If \mathbf{a} is a $p \times 1$ vector of constants and \mathbf{y} is a $p \times 1$ random vector with mean vector $\boldsymbol{\mu}$, then the mean of $z = \mathbf{a}'\mathbf{y}$ is given by*

$$\mu_z = E(\mathbf{a}'\mathbf{y}) = \mathbf{a}'E(\mathbf{y}) = \mathbf{a}'\boldsymbol{\mu}.$$

Theorem 4.2 *Suppose \mathbf{y} is a random vector, \mathbf{X} is a random matrix, \mathbf{a} and \mathbf{b} are vectors of constants, and \mathbf{A} and \mathbf{B} are matrices of constants. Then, assuming the matrices and the vectors in each product are conformable, we have the following expected values:*

(a) $E(\mathbf{A}\mathbf{y}) = \mathbf{A}E(\mathbf{y}).$

(b) $E(\mathbf{a}'\mathbf{X}\mathbf{b}) = \mathbf{a}'E(\mathbf{X})\mathbf{b},$

(c) $E(\mathbf{A}\mathbf{X}\mathbf{B}) = \mathbf{A}E(\mathbf{X})\mathbf{B}.$

4.2 Variances and Covariances

Theorem 4.3 *If \mathbf{a} is a $p \times 1$ vector of constants and \mathbf{y} is a $p \times 1$ random vector with covariance matrix Σ , then the variance of $z = \mathbf{a}'\mathbf{y}$ is given by*

$$\sigma_z^2 = \text{var}(\mathbf{a}'\mathbf{y}) = \mathbf{a}'\Sigma\mathbf{a}.$$

Corollary 4.1 *If \mathbf{a} and \mathbf{b} are $p \times 1$ vectors of constants, then*

$$\text{cov}(\mathbf{a}'\mathbf{y}, \mathbf{b}'\mathbf{y}) = \mathbf{a}'\Sigma\mathbf{b}.$$

Theorem 4.4 *Let $\mathbf{z} = \mathbf{A}\mathbf{y}$ and $\mathbf{w} = \mathbf{B}\mathbf{y}$, where \mathbf{A} is a $k \times p$ matrix of constants, \mathbf{B} is an $m \times p$ matrix of constants, and \mathbf{y} is a $p \times 1$ random vector with covariance matrix Σ . Then*

- (a) $\text{cov}(\mathbf{z}) = \text{cov}(\mathbf{A}\mathbf{y}) = \mathbf{A}\Sigma\mathbf{A}'$,
- (b) $\text{cov}(\mathbf{z}, \mathbf{w}) = \text{cov}(\mathbf{A}\mathbf{y}, \mathbf{B}\mathbf{y}) = \mathbf{A}\Sigma\mathbf{B}'$.