

Parametric Empirical Bayes Rules for Selecting  
the Most Probable Multinomial Event\*

by

Shanti S. Gupta and TaChen Liang  
Purdue University and Wayne State University

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Department of Statistics  
Purdue University

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Abstract

Consider a multinomial population with  $k(\geq 2)$  cells and the associated probability vector  $p = (p_1, \dots, p_k)$ . Let  $p_{[k]} = \max_{1 \leq i \leq k} p_i$ . A cell associated with  $p_{[k]}$  is called the most probable event. We are interested in selecting the most probable event. Let  $i$  denote the index of the selected cell. Under the loss function  $L(p, i) = p_{[k]} - p_i$ , this statistical selection problem is studied via a parametric empirical Bayes approach. Two empirical Bayes selection rules are proposed. They are shown to be asymptotically optimal at least of order  $O(\exp(-c_i n))$  for some positive constants  $c_i$ ,  $i = 1, 2$ , where  $n$  is the number of accumulated past experiences (observations) at hand. Finally, for the problem of selecting the least probable event associated with  $p_{[1]}$  under the loss  $p_i - p_{[1]}$ , two empirical Bayes selection rules are also proposed. The corresponding rates of convergence are found to be at least of order  $O(\exp(-c_i n))$  for some positive constants  $c_i$ ,  $i = 3, 4$ .

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## 1. Introduction

Consider a multinomial population with  $k \geq 2$  cells and the associated probability vector  $\underline{p} = (p_1, \dots, p_k)$  where  $\sum_{i=1}^k p_i = 1$ . Let  $p_{[1]} \leq \dots \leq p_{[k]}$  denote the ordered values of the parameters  $p_1, \dots, p_k$ . It is assumed that the exact pairing between the ordered and the unordered parameters is unknown. Any event associated with  $p_{[k]}$  is considered as the most probable event. A number of statistical procedures based on single samples or sequential sampling rules have been considered in the literature in the classical framework for selecting the most probable event. Bechhofer, Elmaghraby and Morse (1959) have considered a fixed sample procedure through the indifference zone approach. Gupta and Nagel (1967), Panchapakesan (1971) and, Gupta and Huang (1975) have studied this selection problem using a subset selection approach. Cacoullos and Sobel (1966), Alam (1971), Alam, Seo and Thompson (1971), Ramey and Alam (1979, 1980) and Bechhofer and Kulkarni (1984) have considered sequential selection procedures.

We now consider a situation in which one repeatedly deals with the same selection problem independently. In such instances, it is reasonable to formulate the component problem in the sequence as a Bayes decision problem with respect to an unknown (or partially known) prior distribution on the parameter space, and then, use the accumulated observations to improve the decision rule at each stage. This is the empirical Bayes approach due to Robbins (1956, 1964 and 1983).

Empirical Bayes rules have been derived for subset selection goals by Deely (1965). Recently, Gupta and Hsiao (1983) and Gupta and Leu (1988) have studied empirical Bayes rules for selecting good populations with respect to a standard or a control with the

underlying populations being uniformly distributed. Gupta and Liang (1986, 1988) have studied empirical Bayes rules for the problem of selecting the best binomial population or selecting good binomial populations. Many such empirical Bayes procedures have been shown to be asymptotically optimal in the sense that the risk for the  $n$ th decision problem converges to the optimal Bayes risk which could have been obtained if the prior distribution was fully known and the Bayes procedure with respect to this prior distribution was used.

Note that the above mentioned empirical Bayes rules use the so-called nonparametric empirical Bayes approach. That is, one assumes that the form of the prior distribution is unknown. However, in many cases, an experimenter may have some prior information about the parameters of interest, and he would like to use this information to make appropriate decisions. Usually, it is suggested (for example, see Robbins (1964)), that the prior information be quantified through a class of subjectively plausible priors. In view of this situation, in this paper, it is assumed that the parameters of interest in a multinomial distribution follow some conjugate prior distribution with unknown hyperparameters. Under this statistical framework, two empirical Bayes selection rules are proposed. They are shown to be asymptotically optimal at least of order  $O(\exp(-c_i n))$  for some positive constants  $c_i$ ,  $i = 1, 2$ , where  $n$  is the number of accumulated past experiences (observations) at hand. Finally, for the problem of selecting the least probable event associated with  $p_{[1]}$  under the loss  $p_i - p_{[1]}$ , two empirical Bayes selection rules are also proposed. The corresponding rates of convergence are found to be at least of order  $O(\exp(-c_i n))$  for some positive constants  $c_i$ ,  $i = 3, 4$ .

## 2. Formulation of the Problem under the Empirical Bayes Approach

Consider a multinomial population with  $k(\geq 2)$  cells, where the cell  $\pi_i$  has probability  $p_i$ ,  $i = 1, \dots, k$ . Let  $X_i$  denote the observations that arise in the cell  $\pi_i$  based on  $N(\geq 2)$  independent trials. Thus, for given  $\underline{p} = (p_1, \dots, p_k)$ ,  $\underline{X} = (X_1, \dots, X_k)$  has the probability function

$$(2.1) \quad f(\underline{x}|\underline{p}) = \frac{N!}{\prod_{i=1}^k (x_i!)} \prod_{i=1}^k p_i^{x_i},$$

where,  $x_i = 0, 1, \dots, N$  and  $\sum_{i=1}^k x_i = N$ .

For each  $\underline{p}$ , let  $p_{[1]} \leq \dots \leq p_{[k]}$  denote the ordered parameters  $p_1, \dots, p_k$ . It is assumed that there is no apriori knowledge about the exact pairing between the ordered and the unordered parameters. Any cell  $\pi_i$  associated with  $p_{[k]}$  is considered as the most probable event. Our goal is to derive empirical Bayes rules to select the most probable event.

Let  $\Omega = \{\underline{p} | \underline{p} = (p_1, \dots, p_k), 0 < p_i < 1 \text{ and } \sum_{i=1}^k p_i = 1\}$  be the parameter space. It is assumed that  $\underline{p}$  has a Dirichlet prior distribution  $G$  with hyperparameters  $\underline{\alpha} = (\alpha_1, \dots, \alpha_k)$ , where all  $\alpha_i$  are positive but unknown. That is,  $\underline{p}$  has a probability density function of the form

$$(2.2) \quad g(\underline{p}) = \frac{\Gamma(\alpha_0)}{\prod_{i=1}^k \Gamma(\alpha_i)} \prod_{i=1}^k p_i^{\alpha_i - 1}, \quad 0 < p_i < 1, \quad \sum_{i=1}^k p_i = 1,$$

where  $\alpha_0 = \sum_{i=1}^k \alpha_i$ .

Let  $\mathcal{A} = \{i | i = 1, \dots, k\}$  be the action space. When action  $i$  is taken, it means that the cell  $\pi_i$  is selected as the most probable event. For the parameter  $\underline{p}$  and action  $i$ , the

loss function  $L(p, i)$  is defined as

$$(2.3) \quad L(p, i) = p_{[k]} - p_i,$$

the difference between the most probable and the selected event.

Let  $\mathcal{X}$  be the sample space of  $\underline{X} = (X_1, \dots, X_k)$ . A selection rule  $d = (d_1, \dots, d_k)$  is a mapping from  $\mathcal{X}$  into  $[0, 1]^k$  such that for each  $\underline{x} \in \mathcal{X}$ , the function  $d(\underline{x}) = (d_1(\underline{x}), \dots, d_k(\underline{x}))$  is such that  $0 \leq d_i(\underline{x}) \leq 1$ ,  $i = 1, \dots, k$ , and  $\sum_{i=1}^k d_i(\underline{x}) = 1$ . Note that  $d_i(\underline{x})$ ,  $i = 1, \dots, k$  is the probability of selecting cell  $\pi_i$  as the most probable event given  $\underline{X} = \underline{x}$ .

Let  $D$  be the class of all selection rules as defined above. For each  $d \in D$ , let  $r(G, d)$  denote the associated Bayes risk. Then  $r(G) = \inf_{d \in D} r(G, d)$  is the minimum Bayes risk.

For each  $\underline{x} \in \mathcal{X}$ , let

$$(2.4) \quad A(\underline{x}) = \{i | x_i + \alpha_i = \max_{1 \leq j \leq k} (x_j + \alpha_j)\}.$$

Consider the selection rule  $d_G = (d_{1G}, \dots, d_{kG})$  defined below: for each  $i = 1, \dots, k$ ,

$$(2.5) \quad d_{iG} = d_{iG}(\underline{x}) = \begin{cases} |A(\underline{x})|^{-1} & \text{if } i \in A(\underline{x}), \\ 0 & \text{otherwise,} \end{cases}$$

where  $|A|$  denotes the cardinality of the set  $A$ .

It should be noted that in (2.4) any selection rule  $d = (d_1, \dots, d_k)$  satisfying the condition  $\sum_{i \in A(\underline{x})} d_i(\underline{x}) = 1$  is a Bayes selection rule.

A straightforward computation shows that the selection rule  $d_G$  is a randomized Bayes selection rule in the class  $D$ . Since the values of the hyperparameters  $(\alpha_1, \dots, \alpha_k)$  are unknown, it is impossible to apply this Bayes selection rule  $d_G$  for the selection problem

at hand. As we mentioned above, we study this selection problem via empirical Bayes approach.

For each  $j = 1, 2, \dots$ , let  $\underline{X}_j = (X_{1j}, \dots, X_{kj})$  denote the random observations arising from  $N$  independent trials at stage  $j$ . Let  $\underline{P}_j = (P_{1j}, \dots, P_{kj})$  denote the (random) parameters at stage  $j$ . Conditional on  $\underline{P}_j$ ,  $\underline{X}_j$  has a probability function of the form of (2.1). It is assumed that independent observations  $\underline{X}_1, \dots, \underline{X}_n$  are available, and  $\underline{P}_j$ ,  $1 \leq j \leq n$ , have the same prior probability density function of the form (2.2), though not observable. We also let  $\underline{X}_{n+1} = \underline{X} = (X_1, \dots, X_k)$  denote the present observations.

Two empirical Bayes selection rules are proposed depending on whether the value of the parameter  $\alpha_0$  is known or unknown. Note that  $\alpha_0$  is the sum of all the parameters  $\alpha_i$ ,  $1 \leq i \leq k$ . In the case that  $\alpha_0$  is known, the individual values of  $\alpha_i$ ,  $1 \leq i \leq k$ , are still unknown.

First, for each  $i = 1, \dots, k$ , and each  $n = 1, 2, \dots$ , we let

$$(2.6) \quad \begin{cases} \bar{X}_i(n) = \frac{1}{n} \sum_{j=1}^n X_{ij}, M_i(n) = \frac{1}{n} \sum_{j=1}^n X_{ij}^2, Z_i(n) = [N\bar{X}_i(n) - M_i(n)]\bar{X}_i(n), \\ Y_i(n) = [M_i(n) - \bar{X}_i(n)]N - (N-1)(\bar{X}_i(n))^2. \end{cases}$$

When  $\alpha_0$  is known, let

$$(2.7) \quad \hat{\alpha}_{in} = \alpha_0 \bar{X}_i(n) N^{-1},$$

and let

$$(2.8) \quad A_n(x) = \{i | x_i + \hat{\alpha}_{in} = \max_{1 \leq j \leq k} (x_j + \hat{\alpha}_{jn})\}.$$



We then define an empirical Bayes selection rule  $\tilde{d}_n = (\tilde{d}_{1n}, \dots, \tilde{d}_{kn})$  as follows: for each  $i = 1, \dots, k$ ,  $\underline{x} \in \mathcal{X}$ ,

$$(2.9) \quad \tilde{d}_{in}(\underline{x}) = \begin{cases} |A_n(\underline{x})|^{-1} & \text{if } i \in A_n(\underline{x}), \\ 0 & \text{otherwise.} \end{cases}$$

Let  $\mu_{i1} = E[\bar{X}_i(n)]$  and  $\mu_{i2} = E[M_i(n)]$ . Then, following a direct computation, we have  $\mu_{i1} = N\alpha_i\alpha_0^{-1}$ ,  $\mu_{i2} = N\alpha_i\alpha_0^{-1} + (N^2 - N)\alpha_i(\alpha_i + 1)\alpha_0^{-1}(\alpha_0 + 1)^{-1}$ . Hence,  $\alpha_i = L_{i1}L_{i2}^{-1}$ , where  $L_{i1} = (N\mu_{i1} - \mu_{i2})\mu_{i1}$ ,  $L_{i2} = (\mu_{i2} - \mu_{i1})N - (N - 1)\mu_{i1}^2$ . Thus,  $Z_i(n)$ ,  $Y_i(n)$ , and  $Z_i(n)/Y_i(n)$  are moment estimators of  $L_{i1}$ ,  $L_{i2}$ , and  $\alpha_i = L_{i1}L_{i2}^{-1}$ , respectively. Note that  $L_{i1}$  and  $L_{i2}$  are both positive, which can be verified directly by the definition of  $\mu_{i1}$  and  $\mu_{i2}$ . Also,  $Z_i(n) \geq 0$ . However, it is possible that  $Y_i(n) \leq 0$ . Hence, for the case when  $\alpha_0$  is unknown, we first let

$$(2.10) \quad \Delta_{in}(x_i) = \begin{cases} x_i + Z_i(n)/Y_i(n) & \text{if } Y_i(n) > 0, \\ x_i & \text{otherwise.} \end{cases}$$

Also, let

$$(2.11) \quad A_n^*(\underline{x}) = \{i | \Delta_{in}(x_i) = \max_{1 \leq j \leq k} \Delta_{jn}(x_j)\}.$$

We then define an empirical Bayes selection rule  $d_n^* = (d_{1n}^*, \dots, d_{kn}^*)$  as follows: for each  $i = 1, \dots, k$ ,  $\underline{x} \in \mathcal{X}$ ,

$$(2.12) \quad d_{in}^*(\underline{x}) = \begin{cases} |A_n^*(\underline{x})|^{-1} & \text{if } i \in A_n^*(\underline{x}), \\ 0 & \text{otherwise.} \end{cases}$$

In the next section, we will study the optimality of the two sequences of empirical Bayes selection rules  $\{\tilde{d}_n\}$  and  $\{d_n^*\}$ .

### 3. Asymptotic Optimality of Selection Rules $\{\tilde{d}_n\}$ and $\{d_n^*\}$

Consider an empirical Bayes selection rule  $d_n(\underline{x})$ . Let  $r(G, d_n)$  be the Bayes risk associated with the selection rule  $d_n(\underline{x})$ . Then  $r(G, d_n) - r(G) \geq 0$ , since  $r(G)$  is the minimum Bayes risk. The nonnegative difference is always used as a measure of optimality of the selection rule  $d_n$ .

**Definition 3.1.** A sequence of empirical Bayes rules  $\{d_n\}_{n=1}^\infty$  is said to be asymptotically optimal at least of order  $\beta_n$  relative to the prior distribution  $G$  if  $r(G, d_n) - r(G) \leq 0(\beta_n)$  as  $n \rightarrow \infty$ , where  $\{\beta_n\}$  is a sequence of positive values satisfying  $\lim_{n \rightarrow \infty} \beta_n = 0$ .

#### 3.1. Asymptotic Optimality of $\{\tilde{d}_n\}$ .

We first consider the case where  $\alpha_0$  is known. Note that  $\hat{\alpha}_{in}$  is an unbiased estimator of  $\alpha_i$ ; also  $\sum_{i=1}^k \hat{\alpha}_{in} = \alpha_0$  for each  $n = 1, 2, \dots$

For each  $\underline{x} \in \mathcal{X}$ , let  $A(\underline{x})$  be as defined in (2.4) and let  $B(\underline{x}) = \{1, 2, \dots, k\} \setminus A(\underline{x})$ . Thus, for each  $\underline{x} \in \mathcal{X}$ ,  $i \in A(\underline{x})$ ,  $j \in B(\underline{x})$ ,  $x_i + \alpha_i > x_j + \alpha_j$ . Following straightforward computation, we can show

$$(3.1) \quad \begin{aligned} 0 &\leq r(G, \tilde{d}_n) - r(G) \\ &\leq \sum_{\underline{x} \in \mathcal{X}} \sum_{i \in A(\underline{x})} \sum_{j \in B(\underline{x})} P\{x_i + \hat{\alpha}_{in} \leq x_j + \hat{\alpha}_{jn}\}. \end{aligned}$$

Now, for  $i \in A(\underline{x})$ ,  $j \in B(\underline{x})$ ,

$$\begin{aligned} &P\{x_i + \hat{\alpha}_{in} \leq x_j + \hat{\alpha}_{jn}\} \\ &= P\left\{\frac{1}{n} \sum_{m=1}^n \left[\frac{1}{N}(X_{im} - X_{jm}) - \frac{1}{\alpha_0}(\alpha_i - \alpha_j)\right] < -(x_i + \alpha_i - x_j - \alpha_j)\alpha_0^{-1}\right\} \end{aligned}$$

$$\begin{aligned}
(3.2) \quad &\leq P\left\{\frac{1}{n} \sum_{m=1}^n \left[\frac{1}{N}(X_{im} - X_{jm}) - \frac{1}{\alpha_0}(\alpha_i - \alpha_j)\right] < -\varepsilon_{ij}\right\} \\
&\leq \exp\{-n2^{-1}\varepsilon_{ij}^2\} \\
&\leq \exp\{-nc_1\},
\end{aligned}$$

where

$$\begin{aligned}
(3.3) \quad &\varepsilon_{ij} = \min_{x_i, x_j} \{|x_i + \alpha_i - x_j - \alpha_j| \alpha_0^{-1}\}, \quad x_i, x_j = 0, 1, \dots, N, 0 \leq x_i + x_j \leq N, \\
&\quad x_i + \alpha_i - x_j - \alpha_j \neq 0 \\
&> 0 \quad \text{since } N \text{ is a finite number.}
\end{aligned}$$

and

$$(3.4) \quad c_1 = 2^{-1} \min \{\varepsilon_{ij}^2 | i, j = 1, \dots, k, i \neq j\} > 0.$$

In (3.2), the second inequality is obtained using the fact that

$$\begin{aligned}
E\left[\frac{1}{N}(X_{im} - X_{jm}) - \frac{1}{\alpha_0}(\alpha_i - \alpha_j)\right] &= 0, \\
-1 - \frac{1}{\alpha_0}(\alpha_i - \alpha_j) &\leq \frac{1}{N}(X_{im} - X_{jm}) - \frac{1}{\alpha_0}(\alpha_i - \alpha_j) \leq 1 - \frac{1}{\alpha_0}(\alpha_i - \alpha_j)
\end{aligned}$$

and then making use of Theorem 2 of Hoeffding (1963).

By noting that  $\mathcal{X}$  is a finite space, from (3.1) and (3.2), we have the following theorem.

**Theorem 3.1.** Let  $\{\tilde{d}_n\}$  be the sequence of empirical Bayes selection rules defined in (2.9). Then  $r(G, \tilde{d}_n) - r(G) \leq 0(\exp(-c_1 n))$  for some positive constant  $c_1$ .

### 3.2. Asymptotic Optimality of $\{d_n^*\}$ .

For each  $\underline{x} \in \mathcal{X}$ , let  $A(\underline{x})$  and  $B(\underline{x})$  be as defined in the previous sections. For the selection rule  $d_n^*$ , one can obtain the following result

$$(3.5) \quad \begin{aligned} 0 &\leq r(G, d_n^*) - r(G) \\ &\leq \sum_{\underline{x} \in \mathcal{X}} \sum_{i \in A(\underline{x})} \sum_{j \in B(\underline{x})} P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j)\}. \end{aligned}$$

Since  $\mathcal{X}$  is finite, we only need to consider the behavior of  $P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j)\}$  for each  $\underline{x} \in \mathcal{X}$ . Now

$$(3.6) \quad \begin{aligned} &P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j)\} \\ &= P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j) \text{ and } (Z_i(n) \leq 0 \text{ or } Z_j(n) \leq 0 \text{ or } Y_i(n) \leq 0 \text{ or } Y_j(n) \leq 0)\} \\ &\quad + P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j) \text{ and } (Z_i(n) > 0, Z_j(n) > 0, Y_i(n) > 0 \text{ and } Y_j(n) > 0)\}. \end{aligned}$$

Before we go further to study the associated asymptotic behaviors of the above probabilities appearing on the right hand side of (3.6), we need the following lemma.

**Lemma 3.1.** Let  $b > 0$  be a constant. Then,

- a)  $P\{Z_i(n) - L_{i1} < -b\} \leq 0(\exp(-b_i n))$ ; b)  $P\{Z_i(n) - L_{i1} > b\} \leq 0(\exp(-b_i n))$ ;
- c)  $P\{Y_i(n) - L_{i2} < -b\} \leq 0(\exp(-b_i n))$ ; d)  $P\{Y_i(n) - L_{i2} > b\} \leq 0(\exp(-b_i n))$ ;

where  $b_i = b^2 [2N^4(N + \mu_{i1})^2]^{-1} > 0$ .

**Proof:** The techniques used to prove these four inequalities are similar. Here, we give the proof of part a) only.

Note that  $Z_i(n) = [N\bar{X}_i(n) - M_i(n)]\bar{X}_i(n) \geq 0$ . Hence,  $P\{Z_i(n) - L_{i1} < -b\} = 0$  if  $L_{i1} - b \leq 0$ . So, we assume that  $b > 0$  is small enough so that  $L_{i1} - b > 0$ . Then,

$$\begin{aligned}
& P\{Z_i(n) - L_{i1} < -b\} \\
&= P\{N[(\bar{X}_i(n))^2 - \mu_{i1}^2] - [M_i(n)\bar{X}_i(n) - \mu_{i2}\mu_{i1}] < -b\} \\
&\leq P\{\bar{X}_i(n) - \mu_{i1} < -b(2N(N + \mu_{i1}))^{-1}\} \\
(3.7) \quad &+ P\{\bar{X}_i(n) - \mu_{i1} > b(4N^2)^{-1}\} + P\{M_i(n) - \mu_{i2} > b(4\mu_{i1})^{-1}\} \\
&\leq \exp\{-nb^2[2N^4(N + \mu_{i1})^2]^{-1}\} \\
&\quad + \exp\{-nb^2[8N^4]^{-1}\} + \exp\{-nb^2[8N^4\mu_{i1}]^{-1}\} \\
&\leq 0(\exp(-nb_i)).
\end{aligned}$$

Note that in (3.7), the first inequality is obtained from the fact that  $0 \leq \bar{X}_i(n) \leq N, 0 \leq M_i(n) \leq N^2$  and an application of Bonferroni's inequality; the second inequality follows from an application of Theorem 2 of Hoeffding (1963) and the last inequality is obtained from the definition of  $b_i$ .

Hence, the proof of part a) is complete.

By the positivity of  $L_{i1}$  and  $L_{i2}$ , and by Lemma 3.1,

$$\begin{aligned}
& P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j) \text{ and } (Z_i(n) \leq 0 \text{ or } Z_j(n) \leq 0 \text{ or } Y_j(n) \leq 0 \text{ or } Y_i(n) \leq 0)\} \\
(3.8) \quad &\leq 0(\exp(-n \min(b_i, b_j))) \\
&= 0(\exp(-nb_{ij})), \text{ where } b_{ij} = \min(b_i, b_j).
\end{aligned}$$

Therefore, we then only need to consider the asymptotic behavior of  $P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j) \text{ and } (Z_i(n) > 0, Z_j(n) > 0, Y_i(n) > 0 \text{ and } Y_j(n) > 0)\}$ .

Let  $Q_{ij} = (x_i - x_j)L_{i2}L_{j2} + L_{i1}L_{j2} - L_{i2}L_{j1}$ . Then  $Q_{ij} > 0$  if  $i \in A(\underline{x})$  and  $j \in B(\underline{x})$ .

Therefore,

$$\begin{aligned}
& P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j) \text{ and } (Z_i(n) > 0, Z_j(n) > 0, Y_i(n) > 0 \text{ and } Y_j(n) > 0)\} \\
(3.9) \quad & \leq P\{(x_i - x_j)[Y_i(n)Y_j(n) - L_{i2}L_{j2}] < -Q_{ij}/3\} \\
& \quad + P\{Z_i(n)Y_j(n) - L_{i1}L_{j2} < -Q_{ij}/3\} \\
& \quad + P\{Y_i(n)Z_j(n) - L_{i2}L_{j1} > Q_{ij}/3\}.
\end{aligned}$$

With repeated applications of Bonferroni's inequality, we have the following inequalities:

$$\begin{aligned}
& P\{(x_i - x_j)[Y_i(n)Y_j(n) - L_{i2}L_{j2}] < -Q_{ij}/3\} \\
(3.10.a) \quad & \leq P\{Y_i(n) - L_{i2} < -Q_{ij}(6N^4)^{-1}\} + P\{Y_j(n) - L_{j2} < -Q_{ij}(6NL_{i2})^{-1}\} \\
& \quad \text{if } x_i > x_j;
\end{aligned}$$

$$\begin{aligned}
& P\{(x_i - x_j)[Y_i(n)Y_j(n) - L_{i2}L_{j2}] < -Q_{ij}/3\} \\
(3.10.b) \quad & \leq P\{Y_i(n) - L_{i2} > Q_{ij}(6N^4)^{-1}\} + P\{Y_j(n) - L_{j2} > Q_{ij}(6NL_{i2})^{-1}\} \\
& \quad \text{if } x_i < x_j;
\end{aligned}$$

$$(3.10.c) \quad P\{(x_i - x_j)[Y_i(n)Y_j(n) - L_{i2}L_{j2}] < -Q_{ij}/3\} = 0 \quad \text{if } x_i = x_j;$$

$$\begin{aligned}
& P\{Z_i(n)Y_j(n) - L_{i1}L_{j2} < -Q_{ij}/3\} \\
(3.11) \quad & \leq P\{Z_i(n) - L_{i1} < -Q_{ij}(6N^3)^{-1}\} + P\{Y_j(n) - L_{j2} < -Q_{ij}(6L_{i1})^{-1}\};
\end{aligned}$$

and

$$\begin{aligned}
& P\{Y_i(n)Z_j(n) - L_{i2}L_{j1} > Q_{ij}/3\} \\
(3.12) \quad & \leq P\{Y_i(n) - L_{i2} > Q_{ij}(6N^3)^{-1}\} + P\{Z_j(n) - L_{j1} > Q_{ij}(6L_{i2})^{-1}\}.
\end{aligned}$$

Then, by Lemma 3.1 and from Equations (3.9) through (3.12), we conclude that

$$\begin{aligned}
& P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j) \text{ and } (Z_i(n) > 0, Z_j(n) > 0, Y_i(n) > 0 \text{ and } Y_j(n) > 0)\} \\
(3.13) \quad & \leq 0(\exp(-na_{ij})) \text{ for some } a_{ij} > 0.
\end{aligned}$$

Now, from (3.6), (3.8) and (3.13), for each  $\underline{x} \in \mathcal{X}$ ,  $i \in A(\underline{x})$  and  $j \in B(\underline{x})$ ,

$$(3.14) \quad P\{\Delta_{in}(x_i) \leq \Delta_{jn}(x_j)\} \leq 0(\exp(-n \min(b_{ij}, a_{ij}))).$$

Now, let  $c_2 = \min_{i \neq j} \{\min(b_{ij}, a_{ij})\}$ . Then  $c_2 > 0$ .

Based on the preceding, we have the following result.

**Theorem 3.2.** Let  $\{d_n^*\}$  be the sequence of empirical Bayes selection rules defined in (2.12). Then  $r(G, d_n^*) - r(G) \leq 0(\exp(-c_2n))$  for some positive constant  $c_2$ .

**Remark:** Another selection problem related to the multinomial distribution is to select the least probable event; that is, to select the cell associated with  $p_{[1]}$ . If we consider the loss function

$$(3.15) \quad L(\underline{p}, i) = p_i - p_{[1]},$$

the difference between the selected and the least probable event, then under the statistical model described in Section 2, a uniformly randomized Bayes selection rule is

$d_G = (d_{1G}, \dots, d_{kG})$ , where, for each  $i = 1, \dots, k$ ,

$$(3.16) \quad d_{iG} = d_{iG}(\underline{x}) = \begin{cases} |\tilde{A}(\underline{x})|^{-1} & \text{if } i \in \tilde{A}(\underline{x}), \\ 0 & \text{otherwise,} \end{cases}$$

and

$$(3.17) \quad \tilde{A}(\underline{x}) = \{i | x_i + \alpha_i = \min_{1 \leq j \leq k} (\alpha_j + x_j)\}.$$

Let  $\hat{\alpha}_{in}, \Delta_{in}(x_i)$  be defined as in (2.7) and (2.10), respectively. When  $\alpha_0$  is known, we let

$$(3.18) \quad \tilde{A}_n(\underline{x}) = \{i | x_i + \hat{\alpha}_{in} = \min_{1 \leq j \leq k} (x_j + \hat{\alpha}_{jn})\},$$

and define a randomized selection rule  $\tilde{d}_n(\underline{x}) = (\tilde{d}_{1n}(\underline{x}), \dots, \tilde{d}_{kn}(\underline{x}))$  as follows:

$$(3.19) \quad \tilde{d}_{in}(\underline{x}) = \begin{cases} |\tilde{A}_n(\underline{x})|^{-1} & \text{if } i \in \tilde{A}_n(\underline{x}), \\ 0 & \text{otherwise.} \end{cases}$$

When  $\alpha_0$  is unknown, we let

$$(3.20) \quad \tilde{A}_n^*(\underline{x}) = \{i | \Delta_{in}(x_i) = \min_{1 \leq j \leq k} \Delta_{jn}(x_j)\},$$

and define a randomized selection rule  $d_n^*(\underline{x}) = (d_{1n}^*(\underline{x}), \dots, d_{kn}^*(\underline{x}))$  as follows:

$$(3.21) \quad d_{in}^*(\underline{x}) = \begin{cases} |\tilde{A}_n^*(\underline{x})|^{-1} & \text{if } i \in \tilde{A}_n^*(\underline{x}), \\ 0 & \text{otherwise.} \end{cases}$$



Following a discussion analogous to that given earlier for the most probable event, we can see that  $\{\tilde{d}_n\}$  and  $\{d_n^*\}$  are both asymptotically optimal and have the following convergence rates:

$$0 \leq r(G, \tilde{d}_n) - r(G) \leq O(\exp(-c_3n)),$$

$$0 \leq r(G, d_n^*) - r(G) \leq O(\exp(-c_4n)),$$

for some positive constants  $c_3$  and  $c_4$ , where  $r(G)$  now denotes the minimum Bayes risk with respect to the loss function (3.15).

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Consider a multinomial population with $k (\geq 2)$ cells and the associated probability vector $p = (p_1, \dots, p_k)$ . Let $p_{[k]} = \max_{1 \leq i \leq k} p_i$ . A cell associated with $p_{[k]}$ is called the most probable event. We are interested in selecting the most probable event. Let $i$ denote the index of the selected cell. Under the loss function $L(p, i) = p_{[k]} - p_i$ , this statistical selection problem is studied via a parametric empirical Bayes approach. Two empirical Bayes selection rules are proposed. They are shown to be asymptotically optimal at least of order $O(\exp(-c_i n))$ for some			

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positive constants  $c_i$ ,  $i = 1, 2$ , where  $n$  is the number of accumulated past experiences (observations) at hand. Finally, for the problem of selecting the least probable event associated with  $p_{[1]}$  under the loss  $p_i - p_{[1]}$ , two empirical Bayes selection rules are also proposed. The corresponding rates of convergence are found to be at least of order  $O(\exp(-c_i n))$  for some positive constants  $c_i$ ,  $i = 3, 4$ .

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