# A Decision-Theoretic Approach To the Problem of Testing a Null Hypothesis\*

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# A DECISION-THEORETIC APPROACH TO THE PROBLEM OF TESTING A NULL HYPOTHESIS\*

## By Herman Rubin Purdue University

Summary. We consider the testing of the "null hypoth-1. esis"  $\theta = 0$  against the one-dimensional alternative  $\theta \neq 0$ . In most problems, the investigator knows that  $\theta = 0$  is unreasonable, and would prefer to "accept"  $\theta = 0$  if  $|\theta|$  is sufficiently small. We make the assumption that the problem is sufficiently regular, that is, that the likelihood function is sufficiently close to that of a sample from a normal distribution with mean  $\theta$  and variance 1, after normalization if necessary. We give a mathematical formulation of this problem and investigate the solution. It is shown that a crude procedure based on a "small sample" treatment and a "very large sample" treatment can be very bad in the transition region; also, there is not enough information in those treatments to get robust results. Further work is contemplated to see if a small amount of additional information will suffice to obtain robust procedures using only information which the user can reasonably supply.

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2. Mathematical treatment. Let X be the mean of a sample of size n from  $N(\theta,1)$ . Let the weight density for accepting  $\theta = 0$  be  $c\theta^2$ , and let the weight measure for rejecting  $\theta = 0$  be  $\mu$ . Then the risk of accepting if  $|X| < \xi$  is

(1) 
$$\int_{-\infty}^{\infty} \int_{-\xi}^{\xi} c\theta^{2} \sqrt{\frac{n}{2\pi}} e^{-n(x-\theta)^{2}/2} dx d\theta + \int_{|x|>\xi} \sqrt{\frac{n}{2\pi}} e^{-(x-\theta)^{2}/2} d\mu(\theta)$$

Now the first integral in (1) can readily be evaluated as

$$(2) 2c\left(\frac{\xi}{n} + \frac{\xi^3}{3}\right) .$$

Suppose  $\theta = \alpha \phi$ ,  $\mathbf{x} = \alpha \mathbf{y}$ ,  $\xi = \alpha \eta$ ,  $\eta = \alpha^{-2} \mathbf{m}$ . Then (1) becomes

(3) 
$$2c\alpha^{3}(\frac{\eta}{m} + \frac{\eta^{3}}{3}) + \int \int_{|y| > \eta} \sqrt{\frac{m}{2\pi}} e^{-m(y-\phi)^{2}/2} d\mu(\alpha\phi)$$

Suppose  $|\mu| < \infty$ . Then if  $\alpha$  is chosen so that

$$c\alpha^3 = \frac{1}{\sqrt{2\pi}} |\mu| ,$$

and  $dv(\phi) = d\mu(\alpha\phi)/|\mu|$ , the risk is

(5) 
$$|\mu| \left[ \frac{2}{\sqrt{2\pi}} \left( \frac{\eta}{m} + \frac{\eta^3}{3} \right) + v*N(0, \frac{1}{m}) \left( \{y : |y| > \eta \} \right) \right]$$

We will take this as our standard form. Suppose  $\,\nu\,$  is symmetric. Then it is easily seen by differentiating that

(6) 
$$\frac{1}{\sqrt{2\pi}} \left( \frac{1}{m} + \eta^2 \right) = \frac{d v*N(0, \frac{1}{m}) (\eta)}{d\eta}$$

Unfortunately, the solution of this equation for the optimal  $\hat{\eta}$  depends heavily on  $\nu$ . Let us first see what happens in

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two special cases.

The case in which  $\nu$  is concentrated at 0 corresponds to the situation in which there is positive prior probability that  $\theta=0$ , and for any deviation from  $\theta=0$  rejection would be preferred. In this case, (6) becomes

(7) 
$$\frac{1}{\sqrt{2\pi}} \left( \frac{1}{m} + \eta^2 \right) = \frac{\sqrt{m}}{\sqrt{2\pi}} e^{-\frac{1}{2} m \eta^2},$$

so that if  $m \ge 1$  acceptance is possible. (This is the reason for choosing the particular normalization.) Let us call the solution for this case  $n_N$ .

Another case is that in which the sample size is so large that (6) is approximately

(8) 
$$\frac{1}{\sqrt{2\pi}} \quad \eta^2 = \frac{d\nu(\eta)}{d\eta} \quad .$$

This is the case in which sampling error is unimportant and the question is merely whether  $\theta$  is small enough that  $\theta$  = 0 should be accepted. Let the optimal  $\eta$  for this be  $\eta_D$ .

The first simple procedure which comes to mind is to consider  $\eta^* = \max(\eta_N, \eta_D)$ . That this can be very bad is easily seen computationally in the case  $\nu$  normal.

From a theoretical analysis of the problem with 0-th power loss for  $\nu$  normal, a procedure  $\widetilde{\eta}$  suggested itself. Let  $P_N$  be the probability of type I error under the null hypothesis of rejection beyond  $\eta_N$  and let  $P_D$  be the probability of rejection beyond  $\widetilde{\eta}_D$ . Then the probability of rejection beyond  $\widetilde{\eta}_D$  is  $P_N P_D$ . This does not give as good results far away from the critical values of n as  $\eta^*$ , but rarely is much worse if  $\nu$  is normal.

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The optimal procedure  $\hat{\eta}$  and the risks of  $\hat{\eta}$ ,  $\eta^*$ , and  $\tilde{\eta}$  were computed for v N(0, $\sigma^2$ ),  $\sigma^2 = 10^{-k}$ , k = 1(1)20, and  $m = 10^j$ , j = .1(.1)20. The most striking results were at the extreme for  $\sigma^2 = 10^{-20}$  (see table). Note that a sample of "size"  $10^{20}$  is 25,000 times as bad as one of half the size for the crude procedure  $\eta^*$ . One might argue that  $10^{20}$  is too large a sample size; however, there is a scale factor involved, and  $10^{20}$  might correspond to a much smaller sample. However, the bad behavior of the crude procedure holds for  $\sigma^2 < 10^{-3}$ , and a table is included for  $\sigma^2 = 10^{-8}$ .

While the central limit theorem gives us reason to make a normal approximation for the statistic, there does not seem to be a compelling reason for the weight measure  $\nu$  to be normal. Computations with  $\nu$  double-exponential turned out to be feasible, and this was done for scale factors  $10^{-k}$ , k=.5(.5)10 and m as before. As is seen in the enclosed tables for scale factors  $10^{-10}$  and  $10^{-}$  the crude procedure  $\eta^*$  shows the same type of behavior as before, but not as extreme; the procedure  $\widetilde{\eta}$  is not too good, giving risks 45% too high and regrets (excesses of risk over that of knowledge of the parameter) of 80% too high. It is possible to develop an analog of  $\widetilde{\eta}$  for the double-exponential, but then the double-exponential was chosen only for computational convenience, and no clear brief can be made for it.

In the case of  $\nu$  the Cauchy distribution, the only case we have done is for  $m=10^{20}$ ,  $\eta_N=\eta_D$ . Here  $\eta^*$  gives a risk of  $1.56 \times 10^{-27}$ ,  $\hat{\eta}$ ,  $1.55 \times 10^{-27}$ , and  $\tilde{\eta}$ ,  $1.95 \times 10^{-27}$ . This indicates that the tail nature of  $\nu$  near  $\eta_D$  is very important and further investigation is being made of this problem.

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#### References

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$v$ double exponential, scale factor $10^{-4.5}$	$10^{10}  ext{ risk} (\widetilde{\pi})$	31.03	13.88	5.56	3.85	3.29	2.28	1.73	1.45				10 <sup>10</sup> risk (୩)	642.63	29.97	12.96	4.86	2.71	1.76	1.24	1.08	.93
	$10^{10} \mathrm{risk}  (\mathrm{n}^*)$	26.27	11.09	19.97	85.98	24.54	3.24	1.73	1.45			v normal (0,10 <sup>-8</sup> )	$10^{10} \text{ risk (n)}$	637.17	34.44	31.57	369.49	10,860	183.85	3.95	1.37	.93
	$10^{10}$ risk $(\eta)$	26.05	10.39	3.84	2.78	2.46	1.92	1.63	1.45			n v	10 <sup>10</sup> risk (n)	636.50	28.66	12.21	4.53	2.54	1.68	1.21	1.06	.93
	ш	107	107.3	107.7	107.9	108	108.3	108.7	8				Ħ	106	107	107.3	107.7	108	$10^{8.3}$	108.7	109	8
$^{ m v}$ double exponential, scale factor $^{ m 10}$	$10^{26} \; \mathrm{risk} \; (\tilde{\eta})$	402.71	119.92	52.80	26.21	17.89	13.15	9.45	7.75	6.82	6.36		10 <sup>27</sup> risk (♠)	351.48	35.53	13.91	5.77	2.08	1.14	.40		
	10 <sup>26</sup> risk (n <sup>*</sup> )	366.10	97.87	45.64	4,424.52	2,049,000	6,409.12	50.29	9.73	88.9	6.36	v normal (0,10 <sup>-20</sup> )	*	351.01	45.60	85.00	3,194.46	44,893,000	$1.112 \times 10^{12}$	.40		
	10 <sup>26</sup> risk (n)	365.80	96.52	37.01	17.53	12.54	9.94	8.02	7.16	6.70	6.36	mor v	$10^{27} \text{ risk ($\hat{\eta}$)}$	349.35	34.93	13.58	5.60	2.01	1.11	.40		
	Œ	$10^{17.3}$	10,,,	1018	1018.3	1018.5	1018.	$10^{19}$	10 <sup>19.3</sup>	1013.	8		m	1018	1018./	10 19	1019.3	10 <sup>19.</sup>	1050	8		

Table 1

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#### 3 ABSTRACT

We consider the testing of the "null hypothesis"  $\theta=0$  against the one-dimensional alternative  $\theta \neq 0$ . In most problems, the investigator knows that  $\theta=0$  is unreasonable, and would prefer to "accept"  $\theta=0$  if  $|\theta|$  is sufficiently small. We make the assumption that the problem is sufficiently regular, that is, that the likelihood function is sufficiently close to that of a sample from a normal distribution with mean  $\theta$  and variance 1, after normalization if necessary. We give a mathematical formulation of this problem and investigate the solution. It is shown that a crude procedure based on a "small sample" treatment and a "very large sample" treatment can be very bad in the transition region; also, there is not enough information in those treatments to get robust results.