SELECTING GOOD NORMAL REGRESSION MODELS:
AN EMPIRICAL BAYES APPROACH

by

Shanti S. Gupta and TaChen Liang
Purdue University Wayne State University

Technical Report #94-18C

Department of Statistics
Purdue University

August 1994
(Revised December 1994)
SELECTING GOOD NORMAL REGRESSION MODELS:
AN EMPIRICAL BAYES APPROACH*

by
Shanti S. Gupta and TaChen Liang
Department of Statistics Department of Mathematics
Purdue University Wayne State University
West Lafayette, IN 47907-1399 Detroit, MI 48202

Abstract

This paper deals with the problem of selecting all good normal regression models using the parametric empirical Bayes approach. The average of $k$ linear loss functions is used as the loss function for the selection problem, where $k$ is the number of regression models under consideration for the selection problem. Mimicking the behavior of a Bayes selection rule, an empirical Bayes selection rule is constructed. Also, the corresponding asymptotic optimality is investigated. It is shown that under certain conditions on the independent variables of the regression models, the regret risk of the proposed empirical Bayes selection rule converges to 0 with a rate of order $k^{-1}$.

AMS 1991 Subject Classification: Primary 62F07; Secondary 62C12.

Key words and phrases: Asymptotic optimality, Bayes selection rule, empirical Bayes, good population, normal regression model, rate of convergence.

* This research was supported in part by NSF Grant DMS-8923071 at Purdue University.
1. Introduction

Consider \( k \) independent normal populations \( \pi_1 = N(\theta_1, \sigma^2), \ldots, \pi_k = N(\theta_k, \sigma^2) \) with unknown means \( \theta_1, \ldots, \theta_k \) and a common unknown variance \( \sigma^2 \). For a given control value \( \theta_0 \), population \( \pi_i \) is said to be good if \( \theta_i \geq \theta_0 \), and bad otherwise. The problem of selecting all good normal populations has been extensively studied in the literature. To mention some earlier papers, Paulson (1952) and Gupta and Sobel (1958) have studied problems of selecting a subset containing all good populations using some natural selection rules. Randles and Hollander (1971), Miescke (1981) and Gupta and Miescke (1985) have derived optimal selection rules via the \( \Gamma \)-minimax and minimax approaches. Huang (1975) has derived Bayes selection rules to partition normal populations with respect to a control. The reader is referred to Gupta and Panchapakesan (1979, 1985) for an overview on this research area. In this paper, our goal is to derive selection rules for selecting all good normal populations via the parametric empirical Bayes approach.

Let \( \Omega = \{ \theta = (\theta_1, \ldots, \theta_k) | \theta_i \in R, i = 1, \ldots, k \} \) be the parameter space. Let \( \underline{a} = (a_1, \ldots, a_k) \) be an action, where \( a_i = 0, 1, i = 1, \ldots, k \). When action \( \underline{a} \) is taken, it means that population \( \pi_i \) is selected as good if \( a_i = 1 \) and excluded as bad if \( a_i = 0 \). We consider the following loss function:

\[
L(\underline{\theta}, \underline{a}) = \frac{1}{k} \sum_{i=1}^{k} L_i(\theta_i, a_i) \tag{1.1}
\]

where, for each \( i = 1, \ldots, k \),

\[
L_i(\theta_i, a_i) = a_i(\theta_0 - \theta_i)I_{(-\infty, \theta_0)}(\theta_i) + (1 - a_i)(\theta_i - \theta_0)I_{[\theta_0, \infty)}(\theta_i). \tag{1.2}
\]

where \( I_S \) denotes the indicator function of the set \( S \). In (1.2), the first term is the loss of selecting \( \pi_i \) as good while \( \theta_i < \theta_0 \), and the second term is the loss of not selecting \( \pi_i \) when \( \pi_i \) is good.

For each \( i = 1, \ldots, k \), let \( Y_{i1}, \ldots, Y_{im} \) be a sample of size \( m (m \geq 2) \) from population \( \pi_i = N(\theta_i, \sigma^2) \). It is assumed that \( \theta_i \) is a realization of a random variable \( \Theta_i \), which has a \( N(\underline{x}_i^t \underline{\beta}, \tau^2) \) prior distribution, where \( \underline{x}_i = (x_{i1}, \ldots, x_{ip}) \) is a known vector, \( \underline{\beta} = (\beta_1, \ldots, \beta_p) \) is an unknown parameter vector and the variance \( \tau^2 \) is unknown. The random variables \( \Theta_1, \ldots, \Theta_k \) are assumed to be mutually independent. Let \( Y_i = (Y_{i1}, \ldots, Y_{im}) \), \( Y = (Y_1, \ldots, Y_k) \) and let \( \mathcal{Y} \) denote the sample space of \( Y \). A selection rule \( \underline{d} = (d_1, \ldots, d_k) \)
is a mapping defined on the sample space \( \mathcal{Y} \) such that for each \( y \in \mathcal{Y} \), \( d_i(y) \) is the probability of selecting \( \pi_i \) as a good population.

Under the preceding statistical model, the Bayes risk of the selection rule \( \tilde{d} \) is

\[
R(\tilde{d}) = \frac{1}{k} \sum_{i=1}^{k} R_i(d_i)
\]

where

\[
R_i(d_i) = \int_{y \in \mathcal{Y}} d_i(y)[\theta_0 - \varphi_i(y_i)] \prod_{j=1}^{k} f_j(y_j)dy + C_i
\]

and

\[
C_i = E[(\Theta_i - \theta_0)I_{(\theta_0, \infty)}(\Theta_i)],
\]

\( f_j(y_j) \) is the marginally joint probability density of \( Y_j = (Y_{j1}, \ldots, Y_{jm}) \),

\[
\varphi_i(y_i) = E[\Theta_i|Y_i = y_i] = (1 - \alpha)\bar{y}_i + \alpha x_i^\prime \beta = \psi_i(\bar{y}_i)
\]

given \( Y_i = y_i \), where \( \bar{y}_i = \frac{1}{m} \sum_{j=1}^{m} y_{ij} \) and \( \alpha = \sigma^2/(\sigma^2 + \tau^2) \).

Hence, a Bayes selection rule \( \tilde{d}_G = (d_{G1}, \ldots, d_{Gk}) \), which minimizes the Bayes risks among all selection rules, is given as follows:

For each \( y \in \mathcal{Y} \) and each \( i = 1, \ldots, k \),

\[
d_{Gi}(y) = \begin{cases} 1 & \text{if } \psi_i(\bar{y}_i) \geq \theta_0, \\ 0 & \text{otherwise}; \end{cases}
\]

\[
d_{Gi}(y) = \begin{cases} 1 & \text{if } \bar{y}_i \geq [\theta_0 - \alpha x_i^\prime \beta]/(1 - \alpha), \\ 0 & \text{otherwise}. \end{cases}
\]

From (1.5), we see that for each component \( i \), the Bayes selection rule \( d_{Gi} \) is independent of \( y_j, j \neq i \), and depends on \( y_i \) only through the sample mean value \( \bar{y}_i \), and is nondecreasing in \( \bar{y}_i \). Hence it can also be written as \( d_{Gi}(\bar{y}_i) \). The minimum Bayes risk is:

\[
R(\tilde{d}_G) = \frac{1}{k} \sum_{i=1}^{k} R_i(d_{Gi}),
\]

where

\[
R_i(d_{Gi}) = \int_{-\infty}^{\infty} d_{Gi}(\bar{y}_i)[\theta_0 - \psi_i(\bar{y}_i)]g_i(\bar{y}_i)d\bar{y}_i + C_i
\]
and \( g_i(\bar{y}_i) \) is the marginal probability density of the sample mean \( \bar{Y}_i = \frac{1}{m} \sum_{j=1}^{m} Y_{ij} \). It is known that marginally, \( \bar{Y}_i \) follows the normal distribution \( N(\bar{x}'_i \beta, \frac{\sigma^2}{m} + \tau^2) \).

2. Empirical Bayes Selection Rule

It should be noted that the Bayes selection rule \( d_G \) strongly depends on \( \psi_i(\bar{y}_i), i = 1, \ldots, k \), which are also dependent on parameters \( \beta \) and \( \alpha \). Since these parameters are unknown, the Bayes selection rule \( d_G \) cannot be implemented for the selection problem at hand. In the following, the empirical Bayes approach is applied. We first construct estimators for the unknown parameters \( \beta \) and \( \alpha \). Then, by mimicking the behavior of the Bayes selection rule \( d_G \), an empirical Bayes selection rule, say \( d^* \), is derived. The performance of the empirical Bayes selection rule \( d^* \) will be evaluated in the next section.

For each \( i = 1, \ldots, k \), let \( \bar{x}(i) = (\bar{x}_1(i), \ldots, \bar{x}_{i-1}(i), \bar{x}_{i+1}(i), \ldots, \bar{x}_k(i)) \). It is assumed that \( k > p \) and for each \( i = 1, \ldots, k \), \( \bar{x}(i) \) has rank \( p \). Let \( P(i) = \bar{x}'_i(i)\bar{x}(i)\bar{x}'_i(i)^{-1} \bar{x}(i) \). Note that marginally \( \bar{Y}_j \sim N(x'_j \beta, \frac{\sigma^2}{m} + \tau^2) \), \( j = 1, \ldots, k \), and \( \bar{Y}_1, \ldots, \bar{Y}_k \) are mutually independent. Let \( \bar{Y}'(i) = (\bar{Y}_1(i), \ldots, \bar{Y}_{i-1}(i), \bar{Y}_{i+1}(i), \ldots, \bar{Y}_k(i)) \). Under the normal regression model, for each \( i = 1, \ldots, k \), the maximal likelihood estimator of \( \beta \) based on \( \bar{Y}'(i) \) is:

\[
\hat{\beta}(i) = (\bar{x}(i)\bar{x}'(i))^{-1}\bar{x}(i)\bar{Y}'(i).
\]

Next, we construct estimator for \( \alpha = \frac{\sigma^2}{m} / (\frac{\sigma^2}{m} + \tau^2) \). For each \( j = 1, \ldots, k \), let \( W_j = \sum_{\ell=1}^{m} (Y_{j \ell} - \bar{Y}_j)^2 \) and \( W = \sum_{j=1}^{k} W_j \). Since for each \( j = 1, \ldots, k \), \( \frac{W_j}{\sigma^2} \sim \chi^2(m-1) \) and \( W_1, \ldots, W_k \) are iid, therefore, \( \frac{W}{\sigma^2} \sim \chi^2(k(m-1)) \) and \( \frac{W}{mk(m-1)} \) is an unbiased estimator of \( \frac{\sigma^2}{m} \). Let \( V_i = \bar{Y}'(i)(I_{k-1} - P(i))\bar{Y}'(i) \). It is known that \( V_i / (\frac{\sigma^2}{m} + \tau^2) \sim \chi^2(k-1-p) \) and therefore, \( V_i / (k-1-p) \) is an unbiased estimator of \( \frac{\sigma^2}{m} + \tau^2 \). Hence, it is natural to use the ratio \( \frac{W}{mk(m-1)} / (\frac{V_i}{k-1-p}) \) as an estimator of \( \alpha \). However, when \( \alpha \leq 1 \), it is possible that the value of the ratio is greater than one. Hence, we estimate \( \alpha \) by \( \hat{\alpha}(i) = \min(\frac{W}{mk(m-1)} / (\frac{V_i}{k-1-p}), 1) \). We then estimate the posterior mean \( \psi_i(\bar{y}_i) = (1-\alpha)\bar{y}_i + \alpha \bar{x}'_i \beta \) by

\[
\hat{\psi}_i(\bar{y}_i) = [1 - \hat{\alpha}(i)]\bar{y}_i + \hat{\alpha}(i)\bar{x}'_i \hat{\beta}(i)
\]

Now, by mimicking the behavior of the Bayes selection rule \( d_G \), we propose an empir-
ical Bayes selection rule $d^* = (d_1^*, \ldots, d_k^*)$ as follows: For each $i = 1, \ldots, k$ and $y \in \mathcal{Y}$,

$$d_i^*(y) = \begin{cases} 
1 & \text{if } \hat{\psi}_i(y_i) \geq \theta_0, \\
0 & \text{otherwise.} \end{cases} \quad (2.3)$$

Note that the empirical Bayes selection rule $d_i^*$ depends on $y$ only through $\bar{y}_i$, $\hat{\alpha}(i)$ and $\hat{\beta}(i)$, where the latter two are functions of $W$, $V_i$ and $\bar{Y}(i)$. For fixed $\hat{\alpha}(i)$ and $\hat{\beta}(i)$, $d_i^*$ is nondecreasing in $\bar{y}_i$. We let $P_i$ denote the probability measure generated by $W$, $V_i$ and $\bar{Y}(i)$, and let $E_i$ denote the expectation taken with respect to the probability measure $P_i$. Note that $W$, $V_i$, $\bar{Y}(i)$ and $\bar{Y}_i$ are mutually independent. Based on the preceding reasoning, the empirical Bayes selection rule $d^*$ can be presented as:

For each $i = 1, \ldots, k$,

$$d_i^*(\bar{y}_i|\hat{\alpha}(i), \hat{\beta}(i)) = \begin{cases} 
1 & \text{if } \hat{\psi}_i(\bar{y}_i) \geq \theta_0 \\
0 & \text{otherwise.} \end{cases} \quad (2.4)$$

The Bayes risk of the empirical Bayes selection rule $d^*$ can be written as:

$$R(d^*) = \frac{1}{k} \sum_{i=1}^{k} R_i(d_i^*) \quad (2.5)$$

where

$$R_i(d_i^*) = E_i \left[ \int_{\bar{y}_i = -\infty}^{\infty} d_i^*(\bar{y}_i|\hat{\alpha}(i), \hat{\beta}(i))[\theta_0 - \psi_i(\bar{y}_i)]g_i(\bar{y}_i)d\bar{y}_i \right] + C_i$$

$$= \int_{\bar{y}_i = -\infty}^{\infty} P_i\{d_i^*(\bar{y}_i|\hat{\alpha}(i), \hat{\beta}(i)) = 1\}[\theta_0 - \psi_i(\bar{y}_i)]g_i(\bar{y}_i)d\bar{y}_i + C_i. \quad (2.6)$$

3. Asymptotic Optimality

Let $d$ be any selection rule and $R(d)$ the corresponding Bayes risk. Since $d_G$ is the Bayes selection rule $D_i(d_i) = R_i(d_i) - R_i(d_Gi) \geq 0$ for each $i = 1, \ldots, k$. Hence, $D(d) = R(d) - R(d_G) = \frac{1}{k} \sum_{i=1}^{k} D_i(d_i) \geq 0$. $D(d)$ is called the regret risk of the selection rule $d$. The regret risk $D(d)$ is always used as a measure of performance of the selection rule $d$.

**Definition 3.1** A selection rule $d$ is said to be asymptotically optimal of order $\{\varepsilon_k\}$ if $D(d) = O(\varepsilon_k)$ where $\{\varepsilon_k\}$ is a sequence of positive numbers such that $\lim_{k\to\infty} \varepsilon_k = 0$. 

5
In the following, we will study the asymptotic optimality of the empirical Bayes selection rule $d^*$. For this purpose, it is assumed that Condition C holds.

**Condition C** (1) $\sum_{j=1}^{p} x_{ij}^2 < M$ for all $i$ where $M$ is a positive value independent of $k$; (2) $\frac{1}{k} x_i x_i'$ converges to a positive definite matrix $A$ as $k$ tends to infinity; (3) $|\theta_0 - x_i^i \beta| \geq c$ for some positive constant $c$ for all $i = 1, \ldots, k$, and $c$ is independent of $k$.

Now, the regret risk of the empirical Bayes selection rule $d^*$ is

$$D(d^*) = \frac{1}{k} \sum_{i=1}^{k} D_i(d_i^*)$$

(3.1)

where

$$D_i(d_i^*) = E_{\hat{\beta}(i)} \int_{\tilde{y}_i = -\infty}^{\infty} [d_i^*(\tilde{y}_i|\hat{\alpha}(i), \hat{\beta}(i)) - d_{Gi}(\tilde{y}_i)][\theta_0 - \psi_i(\tilde{y}_i)]g_i(\tilde{y}_i)d\tilde{y}_i.$$  

(3.2)

In the following, without loss of generality, it is assumed that $\theta_0 < x_i^i \beta$.

By the definitions of $d_{Gi}$ and $d_i^*$, we obtain that

$$\int_{\tilde{y}_i = -\infty}^{\infty} [d_i^*(\tilde{y}_i|\hat{\alpha}(i), \hat{\beta}(i)) - d_{Gi}(\tilde{y}_i)][\theta_0 - \psi_i(\tilde{y}_i)]g_i(\tilde{y}_i)d\tilde{y}_i$$

$$= \int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)]I[\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(\tilde{y}_i) \geq \theta_0]g_i(\tilde{y}_i)d\tilde{y}_i$$

$$+ \int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)]I[\hat{\alpha}(i) = 1 \text{ and } \hat{\psi}_i(\tilde{y}_i) \geq \theta_0]g_i(\tilde{y}_i)d\tilde{y}_i$$

$$+ \int_{\tilde{y}_i = a_i}^{\infty} [\psi_i(\tilde{y}_i) - \theta_0]I[\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(\tilde{y}_i) < \theta_0]g_i(\tilde{y}_i)d\tilde{y}_i$$

$$+ \int_{\tilde{y}_i = a_i}^{\infty} [\psi_i(\tilde{y}_i) - \theta_0]I[\hat{\alpha}(i) = 1 \text{ and } \hat{\psi}_i(\tilde{y}_i) < \theta_0]g_i(\tilde{y}_i)d\tilde{y}_i$$

$$\equiv I_i + II_i + III_i + IV_i \text{ (say)},$$

where $a_i = (\theta_0 - \alpha x_i^i \beta)/(1 - \alpha)$. Note that $\theta_0 - \psi_i(\tilde{y}_i) \geq 0$ as $\tilde{y}_i < a_i$ and $\psi_i(\tilde{y}_i) - \theta_0 \geq 0$ as $\tilde{y}_i > a_i$. Hence,

$$E_i[II_i] \leq \int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)]g_i(\tilde{y}_i)d\tilde{y}_i E_i[I(\hat{\alpha}(i) = 1)]$$

$$\leq M_1 \exp\left\{-\frac{k(m-1)}{2} \left[\frac{1-\alpha}{2\alpha} - \ell n(1 + \frac{1-\alpha}{2\alpha})\right]\right\}$$

$$+ M_1 \exp\left\{-\frac{k-1-p}{2} \left[-\frac{1-\alpha}{2} - \ell n(1 - \frac{1-\alpha}{2})\right]\right\}$$

$$\leq O(k^{-1}),$$
where, the second inequality is obtained from Lemmas A2(c) and A3(a).

Similarly
\[
E_i[IV_i] \leq \int_{a_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i)d\bar{y}_iE_i[I(\hat{\alpha}(i) = 1)] \leq O(k^{-1}).
\] (3.5)

Next, we consider
\[
E_i[I_i] = \int_{\bar{y}_i=-\infty}^{a_i} [\theta_0 - \psi_i(\bar{y}_i)]g_i(\bar{y}_i)P_i\{\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(\bar{y}_i) > \theta_0\}d\bar{y}_i.
\]

For \( \bar{y}_i < a_i \), by the definition of \( \hat{\psi}_i(\bar{y}_i) \), we have,
\[
P_i\{\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(\bar{y}_i) > \theta_0\}
= P_i\{\hat{\alpha}(i) < 1 \text{ and } (\hat{\alpha}(i) - \alpha)(x'_i\beta - \bar{y}_i) + \hat{\psi}_i(i)(x'_i\beta(i) - x'_i\beta) > \theta_0 - \psi_i(\bar{y}_i)\}
\leq P_i\{\hat{\alpha}(i) < 1 \text{ and } (\hat{\alpha}(i) - \alpha)(x'_i\beta - \bar{y}_i) > \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}
+ P_i\{\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(i)(x'_i\beta(i) - x'_i\beta) > \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}
\equiv I_{i1} + I_{i2}.
\] (3.6)

By Lemma A4(a),
\[
I_{i2} \leq P_i\{x'_i\beta(i) - x'_i\beta > \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}
\leq \frac{\sqrt{2b_i\nu^2}}{\sqrt{\pi(\theta_0 - \psi_i(\bar{y}_i))}}\exp\left\{\frac{-(\theta_0 - \psi_i(\bar{y}_i))^2}{8b_i\nu^2}\right\}
\] (3.7)

where \( b_i = x'_i(x(i)x'(i))^{-1}x_i \) and \( \nu^2 = \frac{\sigma^2}{m} + r^2 \).

Also,
\[
E_i[III_i] = \int_{\bar{y}_i=a_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i)P_i\{\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(\bar{y}_i) < \theta_0\}d\bar{y}_i.
\]

For \( \bar{y}_i > a_i \), by the definition of \( \hat{\psi}_i(\bar{y}_i) \), we have,
\[
P_i\{\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(\bar{y}_i) < \theta_0\}
\leq P_i\{\hat{\alpha}(i) < 1 \text{ and } (\hat{\alpha}(i) - \alpha)(x'_i\beta - \bar{y}_i) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}
+ P_i\{\hat{\alpha}(i) < 1 \text{ and } \hat{\psi}_i(i)(x'_i\beta(i) - x'_i\beta) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}
\equiv III_{i1} + III_{i2}.
\] (3.8)
By Lemma A.4(b),

\[
III_{i2} \leq P_i\{x_i^t\beta(i) - x_i^t\beta < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\} \\
\leq \frac{\sqrt{2b_i v^2}}{\sqrt{\pi}(\psi_i(\bar{y}_i) - \theta_0)} \exp\left\{-\frac{(\psi_i(\bar{y}_i) - \theta_0)^2}{8b_i v^2}\right\}.
\] (3.9)

Combining the preceding results yields that

\[
E[I_i + III_{i}] \leq A_1 + A_2 + A_3
\] (3.10)

where

\[
A_1 = \int_{\bar{y}_i = -\infty}^{\alpha_i} [\theta_0 - \psi_i(\bar{y}_i)]g_i(\bar{y}_i)P_i\{\hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i^t\beta - \bar{y}_i) > \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}d\bar{y}_i,
\]

\[
A_2 = \int_{\bar{y}_i = \alpha_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i)P_i\{\hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i^t\beta - \bar{y}_i) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\}d\bar{y}_i,
\]

and

\[
A_3 = \int_{\bar{y}_i = -\infty}^{\infty} \frac{\sqrt{2b_i v^2}}{\sqrt{\pi}} \exp\left\{-\frac{(\theta_0 - \psi_i(\bar{y}_i))^2}{8b_i v^2}\right\}g_i(\bar{y}_i)d\bar{y}_i.
\]

By noting that \(\bar{Y}_i \sim N(x_i^t\beta, v^2)\) and by Lemma A.5,

\[
A_3 = \sqrt{\frac{8v^2}{\pi}} \frac{b_i}{\sqrt{(1 - \alpha)^2 + 4b_i}} \exp\left\{-\frac{(x_i^t\beta - \theta_0)^2}{2v^2[(1 - \alpha)^2 + 4b_i]}\right\},
\] (3.11)

\[= O(k^{-1}).\]

Therefore, it suffices to consider the asymptotic behavior of \(A_1\) and \(A_2\).

For \(\bar{y}_i < \alpha_i, c(\bar{y}_i) \equiv \frac{\theta_0 - \psi_i(\bar{y}_i)}{2(x_i^t\beta - \bar{y}_i)} = \frac{\theta_0 - x_i^t\beta}{2(x_i^t\beta - \bar{y}_i)} + \frac{1 - \alpha}{2}\) is decreasing in \(\bar{y}_i\), since \(\theta_0 < x_i^t\beta\).

Thus, for \(\bar{y}_i < \alpha_i, c(\bar{y}_i) > c(\alpha_i) = 0\), and by Lemma A.2,

\[
P_i\{\hat{\alpha}(i) < 1 \text{ and } (\hat{\alpha}(i) - \alpha)(x_i^t\beta - \bar{y}_i) > \frac{\theta_0 - \psi_i(\bar{y}_i)}{2}\} \\
\leq P_i\{\hat{\alpha}(i) - \alpha > c(\bar{y}_i)\} \\
\leq \exp\left\{-\frac{k(m - 1)}{2} h_1(c(\bar{y}_i), \alpha)\right\} + \exp\left\{-\frac{k - 1 - p}{2} h_2(c(\bar{y}_i), \alpha)\right\},
\] (3.12)

where \(h_1(c, \alpha) = \frac{c}{2\alpha} - \ell n(1 + \frac{c}{2\alpha})\) and \(h_2(c, \alpha) = -\frac{c}{2(\alpha + c)} - \ell n(1 - \frac{c}{2(\alpha + c)}).\)
By substituting (3.12) into $A_1$ and by Lemma A.6, we obtain

$$
A_1 \leq \int_{\bar{y}_i=-\infty}^{a_i} \left[ \theta_0 - \psi_i(\bar{y}_i) \right] g_i(\bar{y}_i) \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\bar{y}_i), \alpha) \right\} d\bar{y}_i \\
+ \int_{\bar{y}_i=-\infty}^{a_i} \left[ \theta_0 - \psi_i(\bar{y}_i) \right] g_i(\bar{y}_i) \exp\left\{ -\frac{k-1-p}{2} h_2(c(\bar{y}_i), \alpha) \right\} d\bar{y}_i \\
\leq \frac{1}{k} (M_3 + M_4).
$$

(3.13)

Finally, we need to take care of $A_2$. Note that $a_i < x_i^t \beta$ since it is assumed that $\theta_0 < x_i^t \beta$. Thus,

$$
A_2 = \int_{a_i}^{x_i^t \beta} \left[ \psi_i(\bar{y}_i) - \theta_0 \right] g_i(\bar{y}_i) P_i \{ \hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i^t \beta - \bar{y}_i) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2} \} d\bar{y}_i \\
+ \int_{x_i^t \beta}^{\infty} \left[ \psi_i(\bar{y}_i) - \theta_0 \right] g_i(\bar{y}_i) P_i \{ \hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i^t \beta - \bar{y}_i) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2} \} d\bar{y}_i \\
\equiv A_{21} + A_{22}.
$$

(3.14)

For $a_i < \bar{y}_i < x_i^t \beta$, $\theta_0 - \psi_i(\bar{y}_i) < 0$, and

$$
P_i \{ \hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i^t \beta - \bar{y}_i) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2} \} \\
\leq P_i \{ \hat{\alpha}(i) - \alpha < c(\bar{y}_i) \} \\
= 0 \text{ if } \alpha + c(\bar{y}_i) \leq 0.
$$

So, in the following, we consider only those $\bar{y}_i \in (a_i, x_i^t \beta)$ such that $\alpha + c(\bar{y}_i) > 0$, which is equivalent to that $\bar{y}_i < \frac{\alpha x_i^t \beta + \theta_0}{1+\alpha} \equiv \epsilon_i$. Note that $a_i < \epsilon_i < x_i^t \beta$. For $\bar{y}_i \in (a_i, \epsilon_i)$, by Lemma A.2, we have

$$
P_i \{ \hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i^t \beta - \bar{y}_i) < \frac{\theta_0 - \psi_i(\bar{y}_i)}{2} \} \\
\leq P_i \{ \hat{\alpha}(i) - \alpha < c(\bar{y}_i) \} \\
\leq \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\bar{y}_i), \alpha) \right\} + \exp\left\{ -\frac{k-1-p}{2} h_2(c(\bar{y}_i), \alpha) \right\}.
$$

(3.15)

Replacing the inequality of (3.15) into $A_{21}$, and by Lemma A.7, we obtain:

$$
A_{21} \leq \frac{1}{k} (M_5 + M_6).
$$

(3.16)
For \( \tilde{y}_i > x_i' \beta \),

\[
P_i\{ \hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i' \beta - \tilde{y}_i) < \frac{\theta_0 - \psi_i(\tilde{y}_i)}{2} \}
\leq P_i\{ \hat{\alpha}(i) - \alpha > c(\tilde{y}_i) \}
= 0 \text{ if } \alpha + c(\tilde{y}_i) > 1.
\]

So, we consider only those \( \tilde{y}_i > x_i' \beta \) such that \( 0 < c(\tilde{y}_i) < 1 - \alpha \), which is equivalent to that \( \tilde{y}_i > \frac{x_i' \beta - \theta_0}{1 - \alpha} + x_i' \beta \equiv c_i \). Hence, by Lemma A.2, we have,

\[
P_i\{ \hat{\alpha}(i) < 1, (\hat{\alpha}(i) - \alpha)(x_i' \beta - \tilde{y}_i) < \frac{\theta_0 - \psi_i(\tilde{y}_i)}{2} \}
\leq P_i\{ \hat{\alpha}(i) - \alpha > c(\tilde{y}_i) \}
\leq \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\tilde{y}_i), \alpha) \right\} + \exp\left\{ -\frac{k - 1 - p}{2} h_2(c(\tilde{y}_i), \alpha) \right\}.
\]

Replacing (3.17) into \( A_{22} \), by Lemma A.8, we obtain

\[
A_{22} \leq \frac{1}{k}(M_7 + M_8).
\]

We summarize the preceding discussions and results as a theorem as follows.

**Theorem 3.1.** For the normal regression models, it is assumed that Condition C holds. Then, the empirical Bayes selection rule \( \hat{d}^* \) is asymptotically optimal and \( D(\hat{d}^*) = O(k^{-1}) \) as \( k \to \infty \).

4. Appendices

In this section, we present certain results which are useful to study the asymptotic optimality of the empirical Bayes selection rule \( \hat{d}^* \).

**Lemma A.1.** (a) For a standard normal random variable \( Z \) and \( c > 0 \),

\[
P\{ Z \geq c \} \leq \frac{1}{\sqrt{2\pi c}} \exp\left( -\frac{c^2}{2} \right).
\]

(b) For a random variable \( S \sim \chi^2(n) \), we have

\[
P\left( \frac{S}{n} - 1 \leq c \right) \leq \exp\left( -\frac{n}{2} (c - \ell n(1 + c)) \right) \text{ for } -1 < c < 0,
\]
and
\[ P\left( \frac{S}{n} - 1 \geq c \right) \leq \exp\left( -\frac{n}{2} (c - \ell n(1 + c)) \right) \text{ for } c > 0. \]

Note: Part (a) is from Appendix B of Pollard (1984) and part (b) is from Corollary 4.1 of Gupta, Liang and Rau (1994).

**Lemma A.2.** For the random variable \( \hat{\alpha}(i) \) defined previously, we have

(a) \[
P\{\hat{\alpha}(i) - \alpha > c\} \begin{cases} = 0 & \text{if } c > 1 - \alpha, \\ \leq \exp\left\{ -\frac{k(m-1)}{2} h_1(c, \alpha) \right\} + \exp\left\{ -\frac{k-1-p}{2} h_2(c, \alpha) \right\} & \text{if } 0 < c \leq 1 - \alpha, \end{cases}
\]

where \[
h_1(c, \alpha) = \frac{c}{2\alpha} - \ell n\left(1 + \frac{c}{2\alpha}\right)
\]

and \[
h_2(c, \alpha) = -\frac{c}{2(\alpha + c)} - \ell n\left(1 - \frac{c}{2(\alpha + c)}\right).
\]

(b) \[
P\{\hat{\alpha}(i) - \alpha < c\} \begin{cases} = 0 & \text{if } c \leq -\alpha, \\ \leq \exp\left\{ -\frac{k(m-1)}{2} h_1(c, \alpha) \right\} + \exp\left\{ -\frac{k-1-p}{2} h_2(c, \alpha) \right\} & \text{if } -\alpha < c < 0. \end{cases}
\]

(c) \[
P\{\hat{\alpha}(i) = 1\} = P\{\hat{\alpha}(i) - \alpha = 1 - \alpha\} \\
\leq P\{\hat{\alpha}(i) - \alpha \geq 1 - \alpha\}.
\]

**Proof:** By the definition of \( \hat{\alpha}(i) \) and by an application of Lemma A.1(b), straightforward computation will lead the results.

**Lemma A.3.** Under Condition C (1), we have

(a) \[
0 < \int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)] g_i(\tilde{y}_i) d\tilde{y}_i \leq M_1, \text{ and}
\]

(b) \[
0 < \int_{\tilde{y}_i = a_i}^{\infty} [\psi_i(\tilde{y}_i) - \theta_0] g_i(\tilde{y}_i) d\tilde{y}_i \leq M_1,
\]

for all \( i = 1, \ldots, k \), where \( M_1 \) is independent of \( k \).
**Proof:** Straightforward computation will yield the results. Hence the details are omitted.

**Lemma A.4.** For $c > 0$, we have

(a) \[ P_i\{x_i' \hat{\beta}(i) - x_i' \beta > c\} \leq \frac{\sqrt{b_i}v^2}{\sqrt{2\pi c}} \exp\left\{-\frac{c^2}{2b_i v^2}\right\}, \]

where $b_i = x_i'(x(i)x'(i))^{-1}x_i$ and $v^2 = \sigma^2 + \tau^2$.

(b) \[ P_i\{x_i' \hat{\beta}(i) - x_i' \beta < -c\} \leq \frac{\sqrt{b_i}v^2}{\sqrt{2\pi c}} \exp\left\{-\frac{c^2}{2b_i v^2}\right\}. \]

**Proof:** This is a direct application of Lemma A.1(a) by noting that $x_i' \hat{\beta}(i) - x_i' \beta \sim N(0, b_i v^2)$.

**Lemma A.5.** Under Condition C, for sufficiently large $k$,

\[ x_i'(x(i)x'(i))^{-1}x_i \leq \frac{M_2}{k} \quad \text{for some } M_2 > 0 \text{ for each } i = 1, \ldots, k, \]

where $M_2$ is independent of $k$.

**Proof:** Note that $xx' = x(i)x'(i) + x_i'x_i'$. Hence,

\[ \frac{1}{k}xx' = \frac{1}{k}x(i)x'(i) + \frac{1}{k}x_i'x_i', \]

where under Condition C(1), $\frac{1}{k}x_i'x_i' \to 0$ uniformly for each $i = 1, \ldots, k$. Therefore, by Condition C(2), $\frac{1}{k}x(i)x'(i)$ converges to $A$ for each $i = 1, \ldots, k$. Also, since $(\frac{1}{k}x(i)x'(i))(\frac{1}{k}x(i)x'(i))^{-1} = I$, $k(x(i)x'(i))^{-1}$ converges to $A^{-1}$ for every $i = 1, \ldots, k$, and $x_i'k(x(i)x'(i))^{-1}x_i$ converges, as $k \to \infty$, to $x_i' A^{-1} x_i$, which are bounded uniformly for all $i = 1, \ldots, k$, under Condition C(1). That is, $0 \leq x_i' A^{-1} x_i \leq M_2/2$ for all $i = 1, \ldots, k$. Therefore, for sufficiently large $k$,

\[
\begin{align*}
  x_i'(x(i)x'(i))^{-1}x_i &= \frac{1}{k}[x_i'k(x(i)x'(i))^{-1}x_i] \\
  &\leq \frac{2}{k}x_i' A^{-1} x_i \\
  &\leq \frac{M_2}{k}.
\end{align*}
\]
Lemma A.6. Under Condition C(3) and for $k$ being sufficiently large,

(a) \[ \int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)]g_i(\tilde{y}_i) \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\tilde{y}_i), \alpha) \right\} d\tilde{y}_i \leq \frac{M_3}{k} \]

and

(b) \[ \int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)]g_i(\tilde{y}_i) \exp\left\{ -\frac{k-1-p}{2} h_2(c(\tilde{y}_i), \alpha) \right\} d\tilde{y}_i \leq \frac{M_4}{k} \]

for some positive constants $M_3$, and $M_4$, which are independent of $k$.

Proof: (a) Let $z \equiv z(\tilde{y}_i) = \frac{c(\tilde{y}_i)}{2\alpha} = \frac{\theta_0 - \psi_i(\tilde{y}_i)}{4\alpha(z_i^2 - \tilde{y}_i^2)}$. Then $z > 0$ and is decreasing in $\tilde{y}_i$ for $\tilde{y}_i < a_i$ and $dz(\tilde{y}_i) = \frac{(\theta_0 - x_i^2)\beta}{4\alpha(z_i^2 - \tilde{y}_i^2)^2} d\tilde{y}_i$. For $\tilde{y}_i < a_i$, \[ \frac{16\alpha^2(z_i^2 - \tilde{y}_i^2)^3 g_i(\tilde{y}_i)}{(z_i^2 - \theta_0)^2} \leq \frac{32\alpha^2(z_i^2 + \tau^2)}{c\sqrt{\pi}} \equiv c_1 \]

by noting that $\tilde{Y}_i - x_i^2 \beta \sim N(0, \frac{\sigma^2}{m} + \tau^2)$, where $c$ is the constant given in Condition C(3) and $c_1$ is independent of $k$ by Condition C(3). Then

\[
\int_{\tilde{y}_i = -\infty}^{a_i} [\theta_0 - \psi_i(\tilde{y}_i)]g_i(\tilde{y}_i) \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\tilde{y}_i), \alpha) \right\} d\tilde{y}_i \\
= \int_{\tilde{y}_i = -\infty}^{a_i} \frac{16\alpha^2(z_i^2 - \tilde{y}_i^2)^3 g_i(\tilde{y}_i)}{(z_i^2 - \theta_0)^2} z(\tilde{y}_i) \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\tilde{y}_i), \alpha) \right\} dz(-z(\tilde{y}_i)) \\
\leq \int_{\tilde{y}_i = -\infty}^{a_i} c_1 z(\tilde{y}_i) \exp\left\{ -\frac{k(m-1)}{2} h_1(c(\tilde{y}_i), \alpha) \right\} d(-z(\tilde{y}_i)) \\
= c_1 \int_0^{1/4\alpha} z \exp\left\{ -\frac{k(m-1)}{2} [z - \ln(1+z)] \right\} dz.
\]

Note that $h(z) = z - \ln(1+z)$ is increasing in $z$ for $z > 0$, $h(0) = 0$ and as $k$ being sufficiently large $h(1) = 1 - \ln 2 > \frac{2\ln k}{k(m-1)\lambda}$. So, there is a $z^*$, $0 < z^* < 1$, such that $z^* - \ln(1+z^*) = \frac{2\ln k}{k(m-1)\lambda}$. Now

\[
\int_{z=0}^{1/4\alpha} z \exp\left\{ -\frac{k(m-1)}{2} [z - \ln(1+z)] \right\} dz \\
= \int_{z=0}^{z^*} z \exp\left\{ -\frac{k(m-1)}{2} [z - \ln(1+z)] \right\} dz + \int_{z^*}^{1/4\alpha} z \exp\left\{ -\frac{k(m-1)}{2} [z - \ln(1+z)] \right\} dz.
\]

In (A.2), the second term may be negative if $z^* > \frac{1-\alpha}{4\alpha}$. Thus, without loss of generality, it is assumed that $z^* < \frac{1-\alpha}{4\alpha}$.

13
For $0 < z < z^* < 1$, $z - \ln(1 + z) \geq \frac{z^2}{4}$. So,
\begin{equation}
\int_{z=0}^{z^*} z \exp\left\{-\frac{k(m-1)}{2}[z - \ln(1 + z)]\right\}dz \\
\leq \int_{z=0}^{z^*} z \exp\left\{-\frac{k(m-1)z^2}{8}\right\}dz \leq \frac{4}{k(m-1)}.
\end{equation}

By the increasing property of $h(z) = z - \ln(1 + z)$ for $z > 0$ and by the definition of $z^*$, for $z \geq z^*$, $z - \ln(1 + z) \geq z^* - \ln(1 + z^*) = \frac{2\ln k}{k(m-1)}$. Hence,
\begin{equation}
\int_{z^*}^{\frac{1-\alpha}{4\alpha}} z \exp\left\{-\frac{k(m-1)}{2}[z - \ln(1 + z)]\right\}dz \\
\leq \int_{z^*}^{\frac{1-\alpha}{4\alpha}} \frac{1}{2k}\left(\frac{1-\alpha}{4\alpha}\right)^2
\end{equation}

From (A.1)-(A.4) and by taking $M_3 = c_1\left(\frac{4}{m-1} + \frac{1}{2}\left(\frac{1-\alpha}{4\alpha}\right)^2\right)$, the result of part (a) is obtained.

The proof of part (b) is similar to that of part (a). Hence, the detail is omitted here.

**Lemma A.7** Under Condition C(3) and for $k$ being sufficiently large,

(a) \[
\int_{\gamma_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i) \exp\left\{-\frac{k(m-1)}{2}h_1(c(\bar{y}_i), \alpha)\right\}d\bar{y}_i \leq \frac{M_5}{k},
\]

and

(b) \[
\int_{\gamma_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i) \exp\left\{-\frac{k-1-p}{2}h_2(c(\bar{y}_i), \alpha)\right\}d\bar{y}_i \leq \frac{M_6}{k},
\]

where $M_5$ and $M_6$ are positive values independent of $k$.

**Proof:** The proofs are similar to that of Lemma A.6(a). Hence, the details are omitted.

**Lemma A.8.** Under Condition C(3) and for $k$ being sufficiently large

(a) \[
\int_{\gamma_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i) \exp\left\{-\frac{k(m-1)}{2}h_1(c(\bar{y}_i), \alpha)\right\}d\bar{y}_i \leq \frac{M_7}{k},
\]

and

(b) \[
\int_{\gamma_i}^{\infty} [\psi_i(\bar{y}_i) - \theta_0]g_i(\bar{y}_i) \exp\left\{-\frac{k-1-p}{2}h_2(c(\bar{y}_i), \alpha)\right\}d\bar{y}_i \leq \frac{M_8}{k},
\]

where $M_7$ and $M_8$ are positive values independent of $k$. 
References


